# **Monitoring with Sequential Bayesian Inference**

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**Georgia Institute of Technology** 

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Georgia Tech College of Engineering School of Electrical and Computer Engineering

II 4 Seismic



### Motivation

Uncertainties affect accuracy of digital twin model

Ieakages, inaccurate permeability, varying injection rate

Benefits of sequential Bayesian inference

- more information collected along the way
- uncertainty quantification



prediction based on current observation and also all previous observations



<u>Wood et. al, Locked away – geological carbon storage, The Royal Society, October 2022</u> Ringrose, Philip. How to store CO2 underground: Insights from early-mover CCS Projects, 2020.

## Motivation

### Goal: put general statements such as

"It is possible to forecast the likely plume behaviour within reasonable bounds of uncertainty. Precise predictions cannot however be expected, and an interactive modelling approach with model updates based on feedback from regular monitoring data is the right approach for developing CO2 storage projects." by Ringrose

"The monitoring data are often combined with parameterised models of the various flow processes to restrict the range of possible scenarios consistent with the data, but significant uncertainties remain." by Woods

on a firmer theoretical footing.



Li, D., Xu, K., Harris, J. M., & Darve, E. (2020). Coupled time-lapse full-waveform inversion for subsurface flow problems using intrusive automatic differentiation. Water Resources Research, 56, e2019WR027032.



Li, D., Xu, K., Harris, J. M., & Darve, E. (2020). Coupled time-lapse full-waveform inversion for subsurface flow problems using intrusive automatic differentiation. Water Resources Research, 56, e2019WR027032.



# Numerical Experiments

![](_page_5_Picture_2.jpeg)

# **Experiment Setup**

Ground-truth data

Experiment groups

### **1. Unconditioned**

sequential CO<sub>2</sub> saturation data

### 2. Conditioned by seismic

- sequential Bayesian inference
- train conditional normalizing flow

![](_page_6_Picture_10.jpeg)

Ringrose, Philip. How to store CO2 underground: Insights from early-mover CCS Projects, 2020.

## **Experiment Setup**

Transition model  $\mathcal{M}$  (fluid-flow equation)

### stochasticity

varying injection rate I  $[m^3/s]$ 

 $I \sim \mathcal{N}(0, 0.2)$ 

![](_page_7_Figure_6.jpeg)

Figure taken from Ringrose's book Fig. 2.45. Part **b** shows a gradual rising trend in pressure due to geological flow barriers in Tubaen Fm.

![](_page_7_Picture_9.jpeg)

# **Experiment Setup**

### **Sequential experiment:**

- 5 vintages for each group
- each time step is 200 days
- **Seismic setup:** 
  - 8 sources / 200 receivers located on the top of the model
  - generating linear data

![](_page_8_Picture_9.jpeg)

# **Generating Ground Truth**

Model setup & prior generation

- constant acoustic velocity/density
- plumes initialized as circles with saturation s ~  $\mathcal{U}(0.2, 0.8)$

### **Prior** $\mathbf{x} \sim P(\mathbf{x})$

![](_page_9_Figure_6.jpeg)

![](_page_9_Picture_8.jpeg)

### **Generating Ground Truth k** = **0**

![](_page_10_Picture_1.jpeg)

![](_page_10_Figure_2.jpeg)

![](_page_10_Picture_4.jpeg)

# **Generating Ground Truth**

![](_page_11_Figure_1.jpeg)

![](_page_11_Figure_2.jpeg)

### **Transition model's stochasticity comes from varying** injection rate

![](_page_11_Figure_4.jpeg)

![](_page_11_Picture_5.jpeg)

# **Generating Ground Truth**

![](_page_12_Picture_1.jpeg)

![](_page_12_Picture_2.jpeg)

![](_page_12_Picture_3.jpeg)

 $\mathcal{H}$ 

**y**<sup>\*</sup><sub>1</sub>

![](_page_12_Figure_5.jpeg)

### **Observation**

### (seismic image)

![](_page_12_Picture_8.jpeg)

### **Generating Ground Truth k** = **0 k** = 1

![](_page_13_Picture_1.jpeg)

![](_page_13_Picture_2.jpeg)

![](_page_13_Picture_3.jpeg)

 $\mathcal{H}$ 

 $\mathbf{y}_1^*$ 

![](_page_13_Picture_6.jpeg)

![](_page_13_Picture_7.jpeg)

![](_page_13_Picture_9.jpeg)

![](_page_14_Figure_0.jpeg)

![](_page_14_Picture_10.jpeg)

### **Conditional Normalizing Flow (CNF)**

- learn to sample from conditional distribution  $p(\mathbf{x} | \mathbf{y})$
- $\blacktriangleright$  inverse problem: "Given data y, which x corresponds to it?"

![](_page_15_Picture_6.jpeg)

# $p(\mathbf{X} | \mathbf{y})$

![](_page_15_Picture_10.jpeg)

- learn to sample from conditional distribution  $p(\mathbf{x} | \mathbf{y})$
- $\blacktriangleright$  inverse problem: "Given data y, which x corresponds to it?"

![](_page_16_Picture_6.jpeg)

![](_page_16_Picture_9.jpeg)

![](_page_16_Picture_10.jpeg)

- learn to sample from conditional distribution  $p(\mathbf{x} | \mathbf{y})$
- $\blacktriangleright$  inverse problem: "Given data y, which x corresponds to it?"

![](_page_17_Figure_4.jpeg)

![](_page_17_Picture_6.jpeg)

![](_page_17_Picture_9.jpeg)

![](_page_17_Picture_10.jpeg)

- $\blacktriangleright$  Learn to sample from conditional distribution  $p(\mathbf{x} \mid \mathbf{y})$
- Inverse problem: "Given data y, which x corresponds to it?"
- $\blacktriangleright$  CNF: "Given data y, which distribution of data  $\mathbf{x} \sim p(\mathbf{x} | \mathbf{y})$  matches y ?"

![](_page_18_Picture_5.jpeg)

![](_page_18_Picture_7.jpeg)

![](_page_18_Picture_8.jpeg)

![](_page_18_Picture_9.jpeg)

- learn to sample from conditional distribution  $p(\mathbf{x} | \mathbf{y})$
- inverse problem: "Given data y, which x corresponds to it?"
- $\blacktriangleright$  CNF: "Given data y, which distribution of data  $\mathbf{x} \sim p(\mathbf{x} | \mathbf{y})$  matches y?"

![](_page_19_Picture_5.jpeg)

![](_page_19_Picture_7.jpeg)

![](_page_19_Picture_8.jpeg)

Ardizzone, Lynton, et al. "Conditional Invertible Neural Networks for Guided Image Generation." (2019).

## **Conditioned on Seismic**

### **Conditional Normalizing Flow (CNF)**

- learn to sample from conditional distribution  $p(\mathbf{x} | \mathbf{y})$
- Inverse problem: "Given data y, which x corresponds to it?"
- $\blacktriangleright$  CNF: "Given data y, which distribution of data  $\mathbf{x} \sim p(\mathbf{x} | \mathbf{y})$  matches y?"

- neural network training:

$$\hat{\theta} = \arg\min_{\theta} \frac{1}{N} \sum_{n=1}^{N} \left( \|f_{\theta}(\mathbf{x}^{(n)}; \mathbf{y}^{(n)})\|_{2}^{2} - \log \left|\det \mathbf{J}_{f_{\theta}}\right| \right)$$

![](_page_20_Picture_9.jpeg)

Kruse, Jakob, et al. "HINT: Hierarchical invertible neural transport for density estimation and Bayesian inference." *Proceedings of the AAAI Conference on Artificial Intelligence*. Vol. 35. No. 9. 2021.

# Sequential Bayesian Inference

![](_page_21_Figure_2.jpeg)

### Sample from posterior of previous time step, and use it as prior of current time step

![](_page_21_Picture_4.jpeg)

Kruse, Jakob, et al. "HINT: Hierarchical invertible neural transport for density estimation and Bayesian inference." *Proceedings of the AAAI Conference on Artificial Intelligence*. Vol. 35. No. 9. 2021.

# Conditioned - sequential Bayesian $P(\mathbf{x})$ $\downarrow$ $\mathbf{k}=1$ $\mathbf{x}_0$ $\xrightarrow{\mathcal{M}}$ $\mathbf{x}_1$

![](_page_22_Picture_2.jpeg)

Kruse, Jakob, et al. "HINT: Hierarchical invertible neural transport for density estimation and Bayesian inference." Proceedings of the AAAI Conference on Artificial Intelligence. Vol. 35. No. 9. 2021.

![](_page_23_Figure_1.jpeg)

![](_page_23_Picture_3.jpeg)

### Conditioned - sequential Bayesian k=1 CNF Training Block

![](_page_24_Picture_1.jpeg)

![](_page_24_Picture_2.jpeg)

![](_page_24_Picture_3.jpeg)

### Conditioned - sequential Bayesian k=1 CNF Training Block

![](_page_25_Figure_1.jpeg)

![](_page_25_Picture_2.jpeg)

![](_page_25_Picture_3.jpeg)

Image of the neural network is from: Image materials such as neural networks and Deep Learning [WTFPL] for presentations and seminars (http://nkdkccmbr.hateblo.jp/entry/2016/10/06/222245)

### **Conditioned - sequential Bayesian** k=1 **CNF Training Block**

![](_page_26_Figure_2.jpeg)

![](_page_26_Picture_4.jpeg)

![](_page_26_Picture_5.jpeg)

Image of the neural network is from: Image materials such as neural networks and Deep Learning [WTFPL] for presentations and seminars (http://nkdkccmbr.hateblo.jp/entry/2016/10/06/222245)

### **Conditioned - sequential Bayesian** k=1 **CNF Training Block**

![](_page_27_Figure_2.jpeg)

![](_page_27_Picture_4.jpeg)

### k=1 **CNF Training Block**

![](_page_28_Figure_2.jpeg)

### k=n **CNF Training Block**

![](_page_29_Figure_2.jpeg)

Kruse, Jakob, et al. "HINT: Hierarchical invertible neural transport for density estimation and Bayesian inference." Proceedings of the AAAI Conference on Artificial Intelligence. Vol. 35. No. 9. 2021.

![](_page_30_Figure_1.jpeg)

![](_page_30_Picture_3.jpeg)

Kruse, Jakob, et al. "HINT: Hierarchical invertible neural transport for density estimation and Bayesian inference." Proceedings of the AAAI Conference on Artificial Intelligence. Vol. 35. No. 9. 2021.

![](_page_31_Figure_1.jpeg)

![](_page_31_Picture_4.jpeg)

Kruse, Jakob, et al. "HINT: Hierarchical invertible neural transport for density estimation and Bayesian inference." *Proceedings of the AAAI Conference on Artificial Intelligence*. Vol. 35. No. 9. 2021.

![](_page_32_Figure_1.jpeg)

![](_page_32_Picture_2.jpeg)

# Results

![](_page_33_Picture_2.jpeg)

### Unconditioned predict CO<sub>2</sub> plume

unconditioned ensemble mean

**unconditioned sample 1** 

unconditioned sample 2

unconditioned sample 3

![](_page_34_Picture_5.jpeg)

![](_page_34_Picture_7.jpeg)

![](_page_34_Picture_9.jpeg)

### **Conditioned on seismic** predict CO<sub>2</sub> plume Step 1

seismic conditional mean

field observation

seismic conditional sample 1

seismic conditional sample 2

seismic conditional sample 3

![](_page_35_Picture_6.jpeg)

![](_page_35_Picture_7.jpeg)

Step 2

![](_page_35_Picture_8.jpeg)

![](_page_35_Picture_9.jpeg)

![](_page_35_Picture_10.jpeg)

![](_page_35_Picture_11.jpeg)

![](_page_35_Picture_12.jpeg)

![](_page_35_Picture_14.jpeg)

![](_page_35_Picture_16.jpeg)

### **Conditioned on seismic** predict CO<sub>2</sub> plume

ground truth  $\rightarrow x^*$ 

seismic conditional mean

seismic conditional sample variance

unconditioned ensemble mean

unconditioned ensemble variance

![](_page_36_Picture_6.jpeg)

![](_page_36_Picture_8.jpeg)

![](_page_36_Picture_10.jpeg)

### **Conditioned on seismic** predict CO<sub>2</sub> plume

ground truth  $\rightarrow x^*$ 

seismic conditional mean  $\rightarrow E(\mathbf{x}_c \sim p(\mathbf{x} | \mathbf{y}))$ 

$$|\mathbf{x}^* - E(\mathbf{x}_c \sim p(\mathbf{x} \mid \mathbf{y}))|$$

unconditional ensemble mean  $E(\mathbf{x}_{u})$ 

$$|\mathbf{x}^* - E(\mathbf{x}_u)|$$

![](_page_37_Picture_6.jpeg)

![](_page_37_Picture_8.jpeg)

![](_page_37_Picture_9.jpeg)

### Conclusions

### **Unconditioned simulation**

error increases with time

### **Conditioned on seismic with sequential Bayesian inference**

- less variance
- assimilate information and learn along time
- characterize uncertainty

![](_page_38_Picture_7.jpeg)

![](_page_38_Picture_9.jpeg)

# **Future Work**

### **Realistic setup of CO<sub>2</sub> reservoir model**

- real Earth 3D permeability models
- **Conditioned on other observations** 
  - pressure data from wells
  - work with time varying permeability
- Apply technique on scenario leakage for early detection

### more stochasticity: e.g. permeability which we assumed given and fixed

![](_page_39_Picture_12.jpeg)

# Acknowledgement

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![](_page_40_Picture_3.jpeg)

### This research was carried out with the support of Georgia Research Alliance and

# Thank the Diamond sponsors (Equinor ASA, Microsoft Corporation, Occidental

![](_page_40_Picture_6.jpeg)